

$$M_z=\iint_R(xT_y^n-yT_x^n)\,dxdy=T$$

$$\iint_R T_x^n\,dxdy=\pm \iint_R \tau_{xz}\,dxdy=\pm \iint_R \frac{\partial \phi}{\partial y}dxdy$$

$$T=\iint_R(xT_y^n-yT_x^n)\,dxdy=-\iint_R(x\frac{\partial \phi}{\partial x}+y\frac{\partial \phi}{\partial y})\,dxdy$$

$$\iint_R x\frac{\partial \phi}{\partial x}dxdy=\iint_R \frac{\partial}{\partial x}(x\phi)\,dxdy-\iint_R \phi dxdy$$

$$=\oint_S x\phi n_x\,ds-\iint_R \phi dxdy$$

$$\iint_R y\frac{\partial \phi}{\partial y}dxdy=\iint_R \frac{\partial}{\partial y}(y\phi)\,dxdy-\iint_R \phi dxdy$$

$$=\oint_S y\phi n_y\,ds-\iint_R \phi dxdy$$

$$\left(\frac{\partial w}{\partial x}-y\beta\right)n_x+\left(\frac{\partial w}{\partial y}+x\beta\right)n_y=.$$

$$\frac{\partial w}{\partial x}\frac{dx}{dn}+\frac{\partial w}{\partial y}\frac{dy}{dn}=\beta\left(x\frac{dx}{ds}+y\frac{dy}{ds}\right)$$

$$\frac{dw}{dn}=\frac{\beta}{\gamma}\frac{d}{ds}(x^\gamma+y^\gamma)$$

$$T=G\iint_R\left(\beta(x^\gamma+y^\gamma)+x\frac{\partial w}{\partial y}-y\frac{\partial w}{\partial x}\right)dxdy$$

$$J=G\iint_R\left(x^\gamma+y^\gamma+\frac{x}{\beta}\frac{\partial w}{\partial y}-\frac{y}{\beta}\frac{\partial w}{\partial x}\right)dxdy$$

$$\sigma_r=\frac{E}{\gamma-\nu^\gamma}[\varepsilon_r+\nu\varepsilon_\theta-(\gamma+\nu)kT]$$

$$\sigma_\theta=\frac{E}{\gamma-\nu^\gamma}[\nu\varepsilon_r+\varepsilon_\theta-(\gamma+\nu)kT]$$

$$\tau_{r\theta}=\frac{E}{\gamma(\gamma+\nu)}\gamma_{r\theta}$$

$$\varepsilon_z = -\frac{E}{\gamma - \nu} [\nu(\varepsilon_r + \varepsilon_\theta) - (\gamma + \nu)kT]$$

$$e = \varepsilon_r + \varepsilon_\theta + \varepsilon_z = \frac{E}{\gamma - \nu} [(\gamma - \nu)(\varepsilon_r + \varepsilon_\theta) + (\gamma + \nu)kT]$$

$$\sigma_z = \tau_{rz} = \tau_{\theta z} = \gamma_{rz} = \gamma_{\theta z} = \cdot$$

$$\nabla^\gamma(\sigma_r + \sigma_\theta) + E\nabla^\gamma(kT) + (\gamma + \nu)\left(\frac{\partial B_r}{\partial r} + \frac{\gamma}{r}B_r + \frac{\gamma}{r}\frac{\partial B_\theta}{\partial \theta}\right) = \cdot$$

$$\sigma_x + \sigma_y = \frac{\partial^\gamma F}{\partial x^\gamma} + \frac{\partial^\gamma F}{\partial y^\gamma} = \frac{\partial^\gamma F}{\partial r^\gamma} + \frac{\gamma}{r}\frac{\partial F}{\partial r} + \frac{\gamma}{r^\gamma}\frac{\partial^\gamma F}{\partial \theta^\gamma}$$

$$\sigma_r + \sigma_\theta = \frac{\partial^\gamma F}{\partial r^\gamma} + \frac{\gamma}{r}\frac{\partial F}{\partial r} + \frac{\gamma}{r^\gamma}\frac{\partial^\gamma F}{\partial \theta^\gamma}$$

$$F = A_+ \log r + B_+ r^\gamma + C_+ r^\gamma \log r + D_+ r^\gamma \theta + A'_+ \theta$$

$$\begin{aligned} & \frac{A_\gamma}{\gamma} r \theta \sin \theta + (B_\gamma r^\gamma + A'_\gamma r^{-\gamma} + B'_\gamma r \log r) \cos \theta \\ & - \frac{C_\gamma}{\gamma} r \theta \cos \theta + (D_\gamma r^\gamma + C'_\gamma r^{-\gamma} + D'_\gamma r \log r) \sin \theta \\ & + \sum_{n=1}^{\infty} (A_n r^n + B_n r^{n+\gamma} + A'_n r^{-n} + B'_n r^{-n+\gamma}) \cos n\theta \\ & + \sum_{n=1}^{\infty} (C_n r^n + D_n r^{n+\gamma} + C'_n r^{-n} + D'_n r^{-n+\gamma}) \sin n\theta \end{aligned}$$

$$\left(\frac{d^\gamma}{dr^\gamma} + \frac{\gamma}{r} \frac{d}{dr} \right) \left(\frac{d^\gamma F}{dr^\gamma} + \frac{\gamma}{r} \frac{dF}{dr} \right) = \cdot$$

$$\frac{\gamma}{r} \frac{d}{dr} \left\{ r \frac{d}{dr} \left[\frac{\gamma}{r} \frac{d}{dr} \left(r \frac{dF}{dr} \right) \right] \right\} = \cdot$$

$$J(r) = \frac{\gamma}{r^\gamma} \int_{r_+}^r \xi^\gamma \Theta(\xi) d\xi$$

$$\varepsilon_r = \frac{\partial u}{\partial r} = \frac{\gamma}{E} \sigma_r - \frac{\nu}{E} \sigma_\theta$$

$$\varepsilon_\theta = \frac{u}{r} + \frac{\gamma}{r} \frac{\partial v}{\partial \theta} = \frac{\gamma}{E} \sigma_\theta - \frac{\nu}{E} \sigma_r$$

$$\gamma_{r\theta}=\frac{\textcolor{brown}{v}}{r}\frac{\partial u}{\partial \theta}+r\frac{\partial}{\partial r}\left(\frac{v}{r}\right)=\frac{\textcolor{teal}{v}(1+v)}{E}\tau_{r\theta}$$

$$u(r,\theta)=-\frac{1+v}{E}\frac{C}{r}+\frac{1-v}{\mathfrak{E}}Ar\log r-\frac{\mathfrak{v}-v}{\mathfrak{E}}Ar$$

$$+\frac{1-v}{\mathfrak{E}}Br-\frac{1-v^{\mathfrak{r}}}{\mathfrak{E}}r[H(r)-I(r)]+f(\theta)$$

$$v(r,\theta)=-\frac{1+v}{E}\frac{D}{r}-\frac{1+v}{E}r[G(r)-J(r)]+\frac{df}{d\theta}+rg(\theta)$$

$$u(r,\theta)=-\frac{1+v}{E}\frac{C}{r}+\frac{1-v}{\mathfrak{E}}Ar\log r-\frac{\mathfrak{v}-v}{\mathfrak{E}}Ar$$

$$+\frac{1-v}{\mathfrak{E}}Br-\frac{1-v^{\mathfrak{r}}}{\mathfrak{E}}r[H(r)-I(r)]+M\cos\theta+N\sin\theta$$

$$v(r,\theta)=-\frac{1+v}{E}\frac{D}{r}+\frac{A}{E}r\theta-\frac{1+v}{E}r[G(r)-J(r)]$$

$$-M\sin\theta+N\cos\theta+Lr$$

$$H(r)=\frac{1}{\mathfrak{r}}\rho\omega^{\mathfrak{r}}(r^{\mathfrak{r}}-a^{\mathfrak{r}})$$

$$I(r)=\frac{\rho\omega^{\mathfrak{r}}}{\mathfrak{r}r^{\mathfrak{r}}}(r^{\mathfrak{r}}-a^{\mathfrak{r}})$$

$$G(r)=-\frac{1}{\mathfrak{r}}\rho\alpha(r^{\mathfrak{r}}-a^{\mathfrak{r}})$$

$$J(r)=-\frac{\rho\alpha}{\mathfrak{r}r^{\mathfrak{r}}}(r^{\mathfrak{r}}-a^{\mathfrak{r}})$$

$$\frac{C}{b^{\mathfrak{r}}}+\frac{B}{\mathfrak{r}}-\frac{\rho\omega^{\mathfrak{r}}}{\lambda b^{\mathfrak{r}}}(b^{\mathfrak{r}}-a^{\mathfrak{r}})[(\mathfrak{r}+v)b^{\mathfrak{r}}+(1-v)a^{\mathfrak{r}}]=.$$

$$\frac{D}{b^{\mathfrak{r}}}+\frac{\rho\alpha}{\mathfrak{r}b^{\mathfrak{r}}}(b^{\mathfrak{r}}-a^{\mathfrak{r}})=.$$